

Lecture 6: Hyperboloid model

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Goal: M^3 comp hyp with cusps \rightsquigarrow canonical ideal "triangulation" $\left\{ \begin{array}{l} \text{Use to} \\ \text{Solv. homeom} \\ \text{prob.} \end{array} \right.$

Geometry of S^2 : $\langle x, y \rangle = x^t I y = x_1 y_1 + x_2 y_2 + x_3 y_3$

$S^2 = \{x \in \mathbb{R}^3 \mid \langle x, x \rangle = 1\}$ has a Riem. metric

by rest. \langle, \rangle to each $T_p S^2$.

Claim: $\text{Isom}(S^2) = O(3) = \left\{ A \in GL_3 \mathbb{R} \mid \langle Ax, Ay \rangle = \langle x, y \rangle \text{ for all } x, y, \text{ i.e. } A^t A = I \right\}$

Pf: Clearly $O(3) \subseteq \text{Isom}(S^2)$. Now $O(3)$ acts

trans. on S^2 : Any $p \in S^2$ can be moved to $\{x_2 = 0\}$.

by $\begin{pmatrix} \cos t & -\sin t & 0 \\ \sin t & \cos t & 0 \\ 0 & 0 & 1 \end{pmatrix}$ which is rotation about the z-axis

and then to $e_3 = (0, 0, 1)$ by $\begin{pmatrix} \cos t & 0 & -\sin t \\ 0 & 1 & 0 \\ \sin t & 0 & \cos t \end{pmatrix}$.

Moreover, the map $\left(\begin{array}{c} \text{Stab of } e_3 \\ \text{in } O(3) \end{array} \right) \longrightarrow O(T_{e_3} S^2 = \langle e_1, e_2 \rangle)$

is an isom. Thus given any isom f , $\exists A \in O(3)$

s.t. $A \circ f$ fixes e_3 and acts triv on $T_{e_3} S^2$.

By uniqueness of geodesics and the fact that

the exponential map is onto, $A \circ f$ is id_{S^2} .

So $f = A^{-1}$ and $\text{Isom}(S^2) = O(3)$. ▣

Claim: The geodesics on S^2 are great circles, the intersection of S^2 with a plane through 0.

Pf: Enough to show for $P = \{z = 0\}$ since $O(3)$ acts trans on such planes (as it does so on their normal vecs).

Now P is fixed by $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$ and let γ be unique geod. with $\gamma'(0) = (0, 1, 0) \in T_{(1,0,0)} S^2$.

Since A fixes $\gamma'(0)$, it fixes γ pointwise $\Rightarrow \gamma = P \cap S^2$. \square

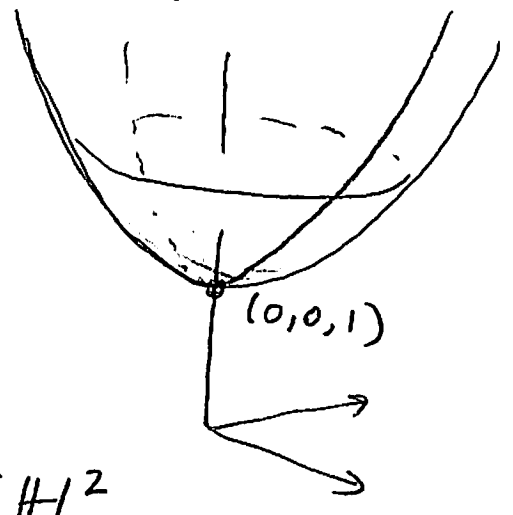
Geometry of \mathbb{H}^2 : $\langle x, y \rangle = x^t J y$ for $J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$
 $= x_1 y_1 + x_2 y_2 - x_3 y_3$

$\mathbb{H}^2 = \left\{ x \in \mathbb{R}^3 \mid \langle x, x \rangle = -1 \iff x_1^2 + x_2^2 = x_3^2 - 1 \right.$
 $\left. \text{and } x_3 > 0. \right\}$

Set $O(2,1) = \left\{ A \in GL_3 \mathbb{R} \mid \begin{array}{l} A \text{ pres } \langle \cdot, \cdot \rangle \\ \text{i.e. } A^t J A = J \end{array} \right\}$

which pres $\{ \langle x, x \rangle = -1 \}$. Let

$O_0(2,1)$ be the subgroup pres \mathbb{H}^2 .



Claim: The rest of $\langle \cdot, \cdot \rangle$ to each $T_p \mathbb{H}^2$ is pos. def, making it a Riem. mfd.

Moreover $Isom(\mathbb{H}^2) = O_0(2,1)$.

Pf: $O_0(2,1)$ acts trans on \mathbb{H}^2 since

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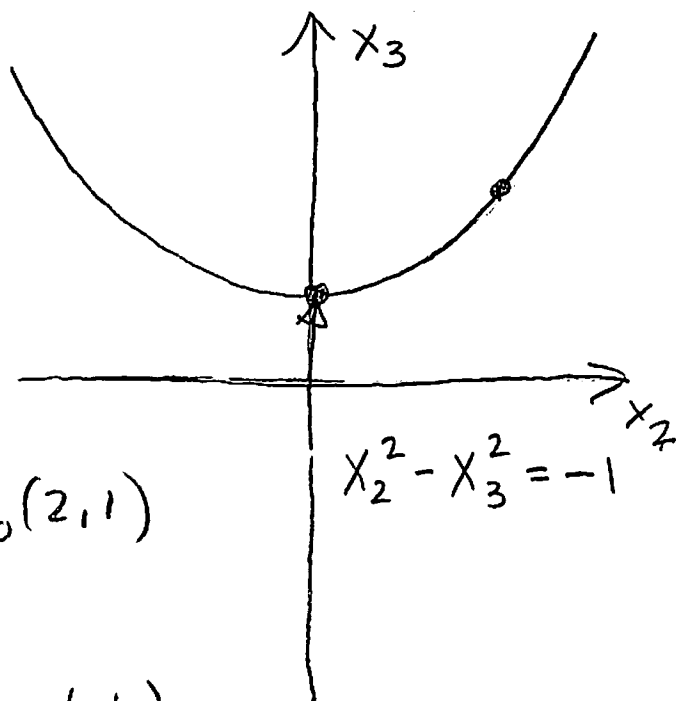
a) $O_0(2,1) \cong \left\{ \begin{pmatrix} O(2) & 0 \\ 0 & 0 & 1 \end{pmatrix} \right\}$ so any $p \in \mathbb{H}^2$ can be rotated so that $x_1 = 0$

b) Param the hyp $x_1 = 0$

$$\text{by } x_2 = \sinh(t) = \frac{1}{2}(e^t - e^{-t})$$

$$\text{and } x_3 = \cosh(t) = \frac{1}{2}(e^t + e^{-t})$$

Then $\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cosh t & \sinh t \\ 0 & \sinh t & \cosh t \end{pmatrix}$ is in $O_0(2,1)$



and takes e_3 to $(0, \sinh t, \cosh t)$.

So $\langle , \rangle|_{T_p \mathbb{H}^2}$ is pos. def since $\langle , \rangle|_{T_{e_3} \mathbb{H}^3} = x_1^2 + x_2^2$

The rest is the same as for S^2 . ▣

Again, if P is a plane through 0 , then $P \cap \mathbb{H}^2$ is a geodesic when $\neq \emptyset$. Also, $\gamma(t) =$

$(0, \sinh t, \cosh t)$ is a unit speed geod:

$$\gamma' = (0, \cosh t, \sinh t) \Rightarrow \langle \gamma', \gamma' \rangle = \cosh^2 t - \sinh^2 t = 1.$$

Claim: $\text{dist}_{\mathbb{H}^2}(x, y) = \cosh^{-1}(-\langle x, y \rangle)$

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(cf: $\text{dist}_{\mathbb{S}^2}(x, y) = \cos^{-1}(\langle x, y \rangle)$).

Pf: Using A in $O_0(2, 1)$, can assume $x = e_3$

and y has $y_1 = 0$ and $y_2 > 0$. Then $-\langle x, y \rangle = +y_3$
 $= \cosh(t)$ where $t = \text{dist}_{\mathbb{H}^2}$ as γ is unit-speed. \square

Comments: 1) To define \mathbb{H}^n , use $\mathbb{R}^{n,1}$ with

$$\langle x, y \rangle = x_1 y_1 + \dots + x_n y_n - x_{n+1} y_{n+1}. \text{ Note } \mathbb{H}^n$$

has many \mathbb{H}^k 's in it — just intersect with a subsp.

through 0.

2) $\text{Isom}^+(\mathbb{H}^n) = SO_0(n, 1)$,

Also circum. of circle
of radius t is $2\pi \sinh t$.
 $\approx \pi e^t$ for large t !

3) $\Gamma \backslash \mathbb{H}^n$ for $\Gamma = SO_0(n, 1) \cap SL_{n+1} \mathbb{Z}$
gives a hyp. orbifold with finite
volume and cusps.

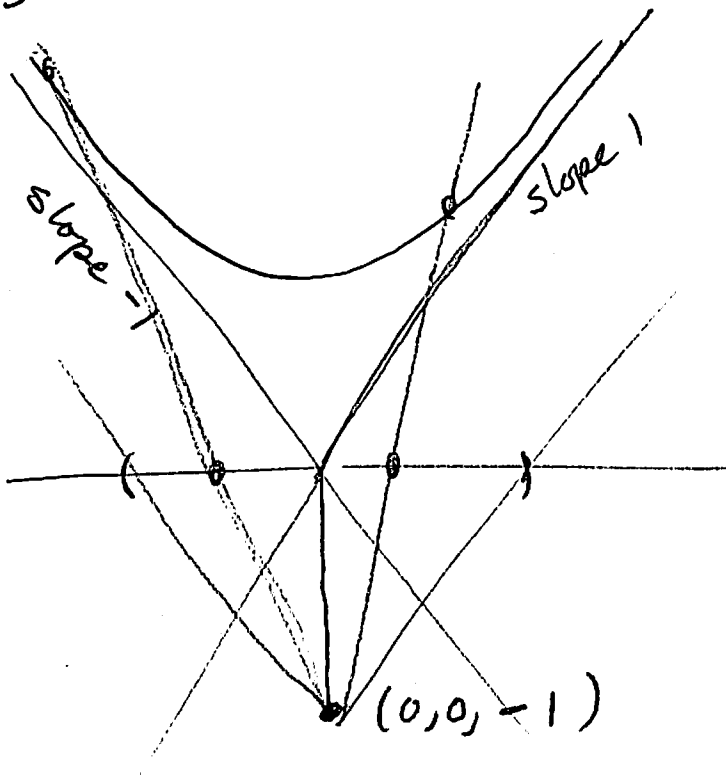
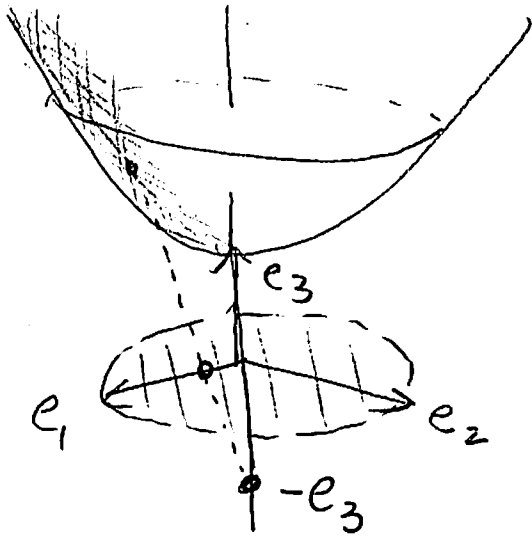
4) Great for computation — its just matrices!

5) Also, \mathbb{H}^n is complete (as a metric space

\Leftrightarrow as a Riem. manifold.) as closed balls are cpt.

Back to $n=2$: How does this connect to the Poincaré model?

Stereographically project onto open unit disc in $x_3 = 0$ plane towards $-e_3$.



Not so hard to write out and calc. that this is an isom...